

# LK8000 version 6.0

*What's new and what has changed since v5.0*

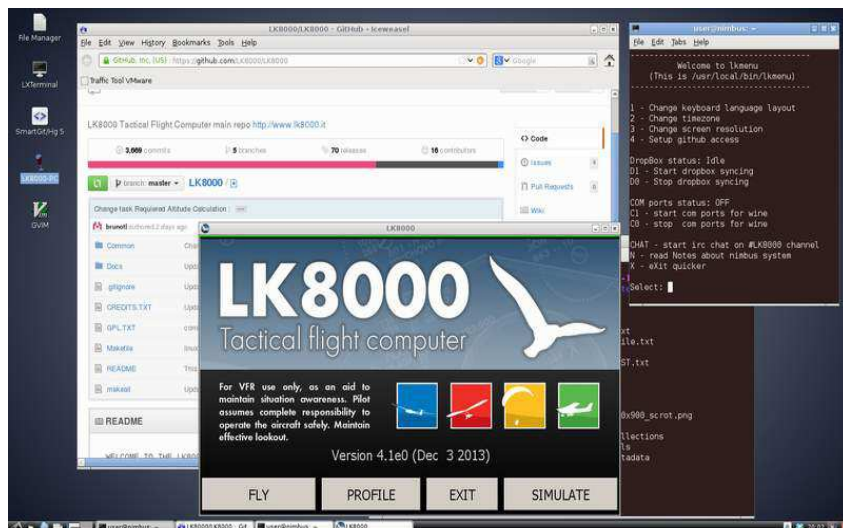
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September 2016

## Overview of the new LK8000 v6.0

The entire code base has been revised to adopt a common cross-platform set of functions and libraries, and it now compiles and runs natively on Linux architectures aside Windows, thanks to Bruno de Lacheisserie. We have now LK for native Linux, Kobo, Apple iOS, Raspberry PI, and more coming!

We delivered a virtual machine named “Nimbus” to allow developers and enthusiasts to compile and customize the software with minimal efforts and without particular knowledge of programming.

Nimbus was delivered in January 2015, as a priority step for team development.



While focusing on adapting the code for new operating systems, we also strove to keep efficiency and reliability inherited from version 5.0. As a result, the new 6.0 is even faster than any previous version, and it can still run on slow CPU hardware: it is perfectly usable on 360Mhz RISC processors and it could be installed on ancient early PPC 2002 pocket computers, if we had one to test on!

Since new hardware can be delivered with several screen resolutions, we had to support all kind of geometries; for this reason a considerable amount of time has been spent to make LK shine on any resolution, and any orientation. In the past, “portrait” mode was considered a second choice, after landscape, but now they are both equally good.

It is now possible to choose font sizes for most items of the user interface, and LK will automatically adapt the look and feel without the need to restart; results are instantly visible.

A much desired feature we accomplished was to let people be able to change the overlays .

Functionally, there are several precious improvements and many small bug fixes.

A final word about the Linux version for Kobo e-readers: we found some compromises changing original colors to dithered grey-scale colors, in order to make it better – if possible. The lack of colors is quite compensated by a perfect readability under the sun light of e-ink screens, and many paragliding pilots have been using earlier alpha versions of LK since many months with satisfaction.

Happy flights, and safe landings

The LK8000 Development Team

## Nimbus development system

We all know too well how complicated it is to install a development platform to be able to "compile" (generate executable machine code) something. As developers, we had some bad times in the past helping people to join us on the source code, not to mention the fact that we were all testing on different environments.

While migrating to linux, as a first step towards other operating systems, we felt it was time to settle and solve this problem once and forever.

We want that anybody, even non-techies people, can compile its own version of LK, and change it if they want to do it. Or at least, they can try on that too!

We want that new developers can jump on the project without the hassle of installing tons of things and packages, and be ready to go in less than 30 minutes, most of them spent on a simple single download of a file.

We wanted a friendly environment, exactly the same for all of us, consolidated and easy to maintain.

The only possible approach to fulfill all of this is to provide to everybody a computer, preinstalled, with nothing else to do but run it and find everything in it ready to be used.

Of course, we cannot ship a real computer. We ship a virtual machine instead. This is "nimbus".

Nimbus is a **debian 7 linux virtual machine**, preinstalled and preconfigured, running under VmWare player (free of charge).

It is 1.8G file, 7z format, uncompressed is about 8G.

It uncompress in one folder, and you simply open that folder in vmware player. Nimbus is ready to be run.

There is a quick lkmenu to make things easier that automatically appears on startup. We have notes and instructions inside.

We have DropBox shared filesystem: what you copy in /lk/DropBox appears automatically on other nimbus.

To send a file, or to distribute an NMEA log, it is just as simple as copying it there. (This feature is reserved to active official developers).

We have wine and LK installed, running PC version perfectly. COM1,2,3,4 are available and a gps simulator and NMEA replicator that can feed LK with nmea logs.

It is really an amazing approach to development, also exceptional for new people. Just consider that to compile LK , after login, you simply have to:

```
cd /lk/github/LK8000
make TARGET=PNA
mv LK8000-PNA.exe /shared
```

That's right, after login only 3 commands are needed, to expose a new compiled version inside your windows machine. Your own LK!

There is also an embedded chat system inside, to talk to other developers. And all of this can fit on a USB pen drive with at least 8G of space, if you want to "bring the development system" with you around, and run it on different computers.

It does not need much computing power, and it can be run also inside another linux machine: it is a virtual environment, running in only 256 M (mega) of ram (best with 512M).

Nimbus can compile LK for all platforms under developments: PC, PNA, PPC2002, PPC2003, native LINUX and ARM LINUX - KOBO.

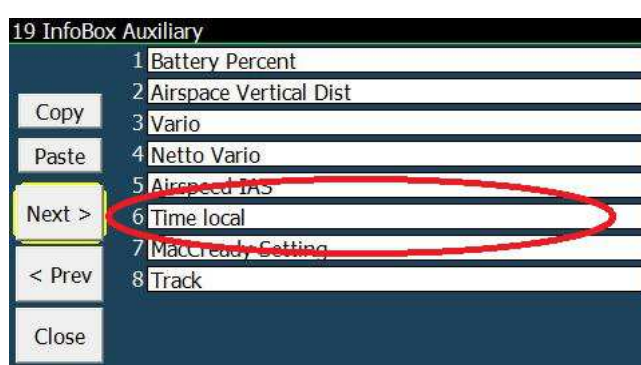
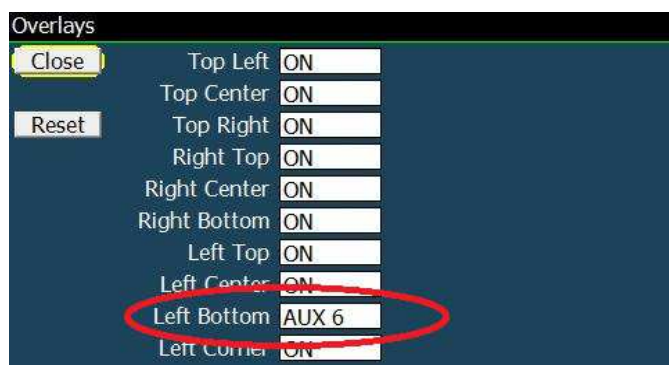
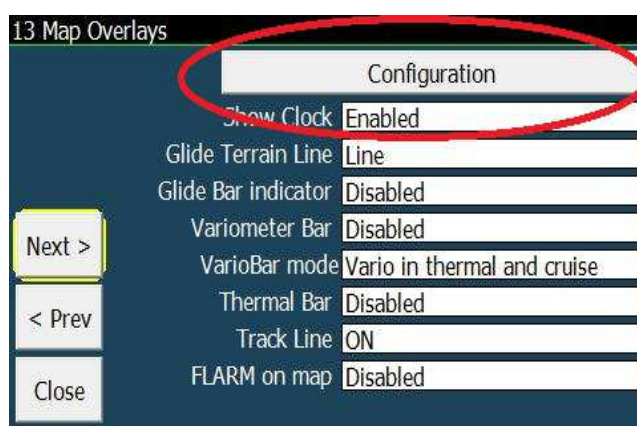
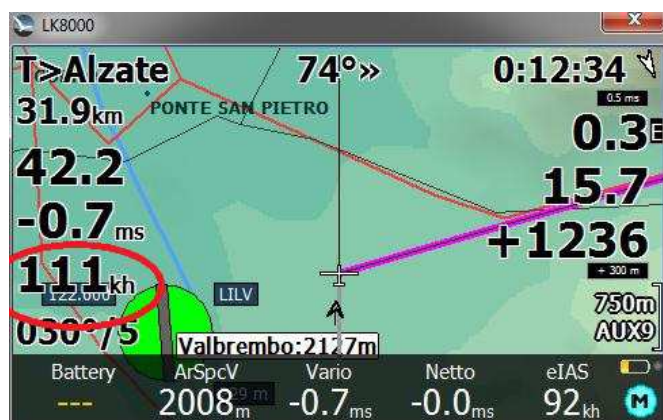
You can download Nimbus as a 7z file from <http://www.tinyurl.com/LK8000-NIMBUS>  
You need also Vmware Player or Workstation ([www.vmware.com](http://www.vmware.com)) .

Watchout, the download takes some time since you are going to fetch 1.8 gigabytes at once.

You can join the development community on Whatsapp, get in touch with us for details.

## Overlays configuration

Overlays for gliders have gained a new field, previously available only during thermal mode. For paragliding this field was already enabled. By default it is showing ground speed. In LK 6.0 all overlays can be customized! Enter system configuration, and go to menu 13.

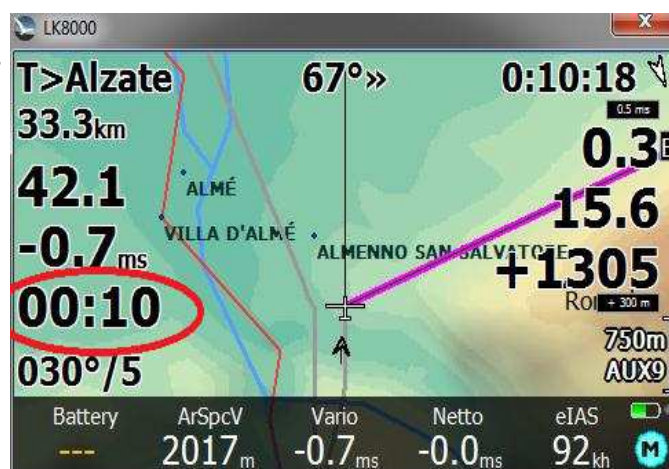


Overlays Top (Left,Center,Right) cannot be changed, only enabled or disabled. Overlays Right Top can be enabled, disabled, or changed to AUX 1. Right center can be changed also to AUX 2, and so on till Left Corner, AUX7. These AUX values are the same used by the AUX bottombar, and they are configurable in menu 19. In the example we change Left bottom to AUX6, and configure AUX6 to be Time Local.

Since we can enable-disable each overlay, there is no more a configurable option for "Full overlays" or "Half overlays" like we had until v5.

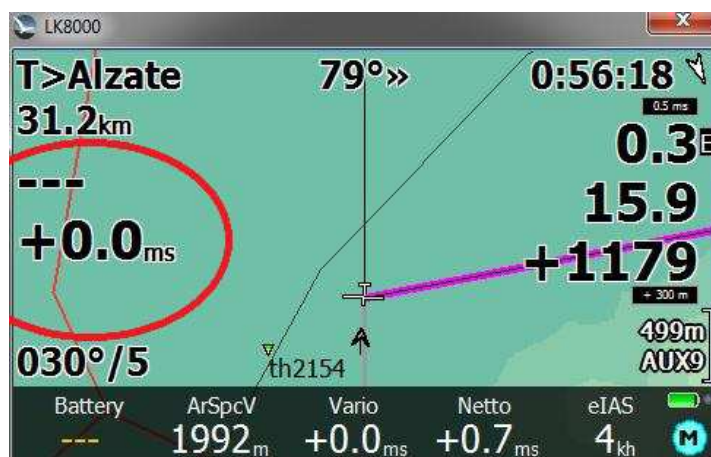
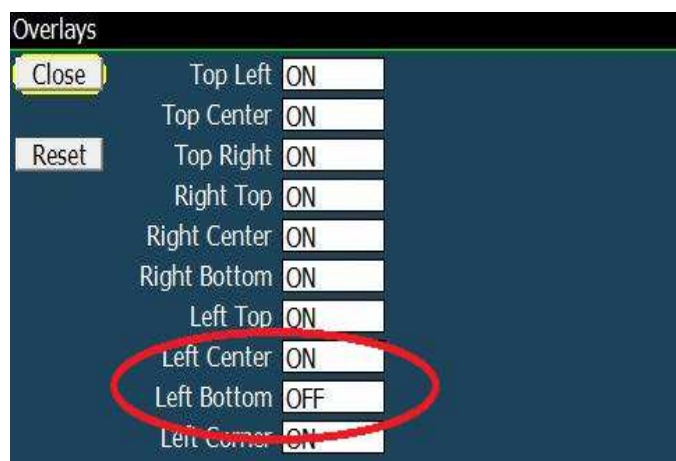
And we also do not have anymore the "Font size" configuration for overlays in page 13: previously they could be only big font or small font. Now we can do much better!

Please notice that we still have "show clock", because if you set it off it will be replaced by the distance (33.3km in the example). Top Right can be a clock or the distance, depending on that choice, as before.





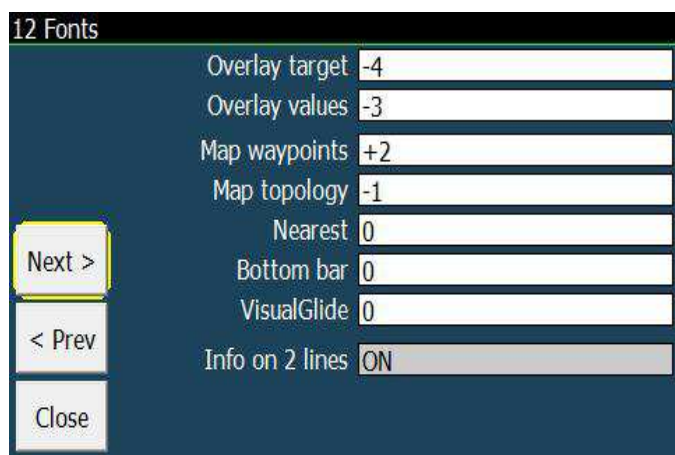
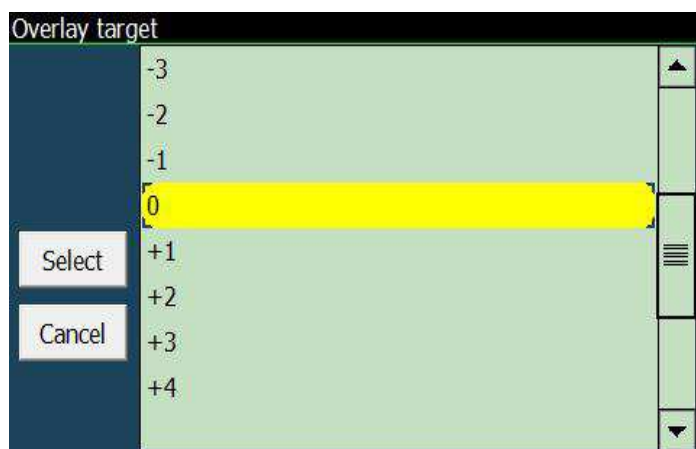
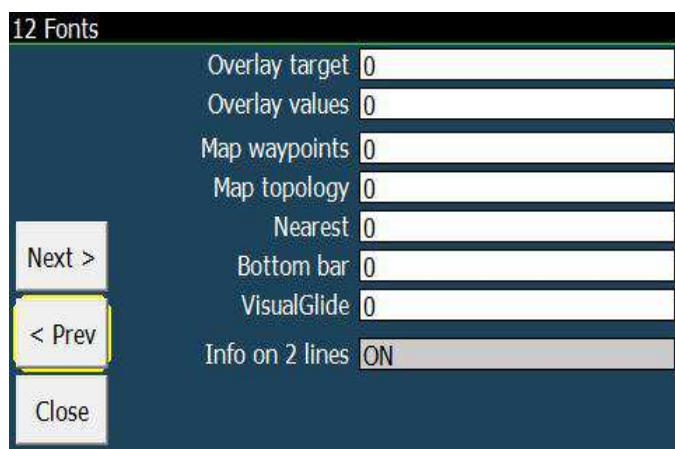
If you disable the Left Bottom overlay, then Left top and Left Center will dispose themselves with better spacing for optimal readability.



## Configurable Font sizes

The beauty of LK v6 is that you can change font sizes without any trouble, with instant results and no need to restart the software. LK will dynamically reposition all overlays for the the best look.

Fonts are changed using a scale from -10 to +10, with 0 being the default , in system configuration menu 12.



Overlay target will change both Top overlays AND the wind overlay, named Left Corner.

Overlay values are the values of course; notice that the safety indicators are not affected by changes, since their size is calculated automatically for safety reasons, hence their name!

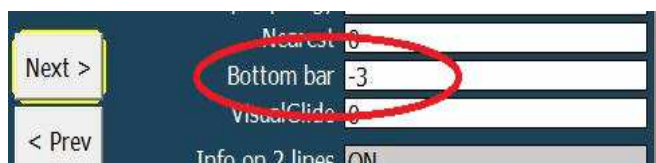
Depending on how far you position the device from your eyes, you may need bigger or smaller fonts.

LK will do its best to try and reposition all items without overlapping, but of course you cannot double the size of all overlays if they cannot fit in the screen. No miracles.

A different matter is for Map waypoints and topology items: they are automatically printed leaving space for each other without overlapping, and if you reduce size you will also see more items on screen. The "decluttering engine" in system menu 3 map display will do the rest.

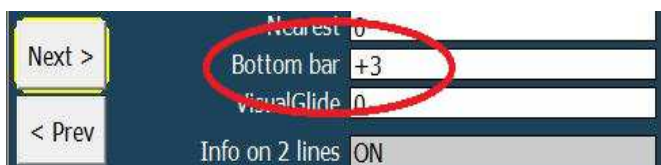
## Bottom bar size

In menu 12 you can change the size of bottom bar fonts.



If you reduce size, there is some space available and LK will try to use it, adding more items.

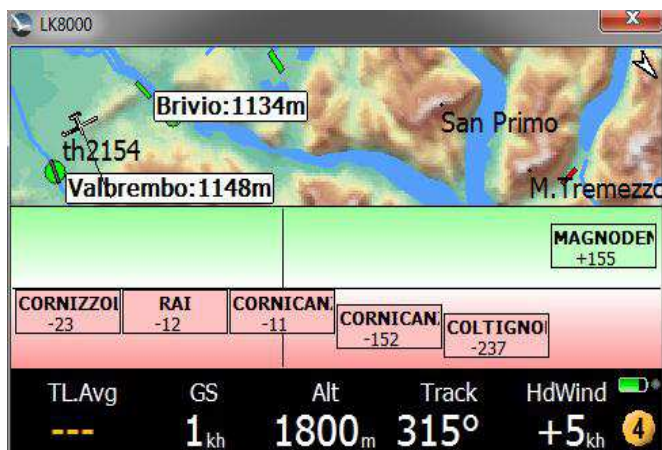
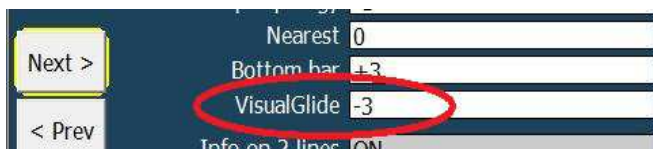
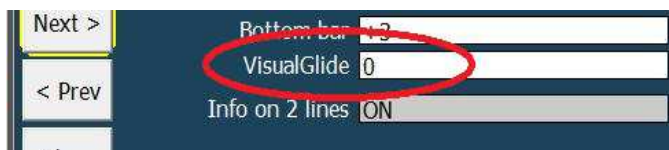
If you enlarge font size, there is less space and some items will be removed.



They all fit perfectly in any case!

## VisualGlide size

Like for the bottom bar, also VisualGlide will make use of available space if you reduce font size.

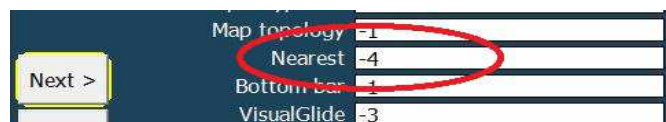
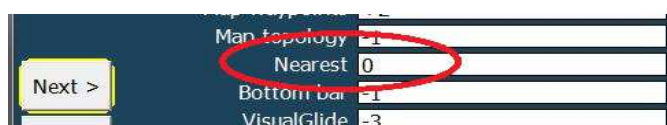




## Nearest pages font size

The “nearest” as we all know are the list of waypoints in 2.1 2.2 3.1 etc.

They also apply to airspaces list page 2.4 of course.



	Distance	Direction	ReqEff	AltArr
VALBREMBO	4.8	123°»	3.7	+1146
KONG	8.8	« 7°	6.8	+1074
SKYANGELS	12.4	«118°	9.7	+981
ORIO	13.8	157°»	10.9	+908
BAIALUPO	18.0	«127°	13.3	+917
CAREAS	25.4	«160°	18.2	+770

TL.Avg GS Alt Track HdWind E.20s  
--- 1<sub>kh</sub> 1800<sub>m</sub> 315° +5<sub>kh</sub> oo

	Distance	Direction	ReqEff	AltArr
VALBREMBO	4.8	123°»	3.8	+1146
KONG	8.8	« 7°	6.8	+1074
SKYANGELS	12.4	«118°	9.7	+981
ORIO	13.8	157°»	10.9	+908
BAIALUPO	18.0	«127°	13.3	+916
CAREAS	25.4	«160°	18.2	+769
CARAVAGGIO	27.1	«154°	19.5	+726
ARZAGO	28.4	«142°	20.9	+670

TL.Avg GS Alt Track HdWind E.20s  
--- 1<sub>kh</sub> 1800<sub>m</sub> 315° +5<sub>kh</sub> oo

## Info on two lines in Portrait mode nearest pages

By selecting “Info on two lines” ON, you will get a more usable list of items, and a much bigger area to click on with your finger. Fonts are automatically bigger with two lines, and you can experiment also reducing font size while using two lines.

	Dist	Dir	rEff	AltA
VALBREMBO	5.0 km			
127°»	3.9			+1141 m
KONG	8.4 km			
« 7°	6.5			+1084 m
SKYANGELS	12.6 km			
«119°	9.8			+976 m
ORIO	14.2 km			
157°»	11.2			+899 m
BAIALUPO	18.2 km			
«128°	13.5			+911 m
CAREAS	25.7 km			
«160°	18.5			+760 m
CARAVAGGIO	27.5 km			
«154°	19.8			+718 m

TL.Avg GS Alt Track  
--- 1<sub>kh</sub> 1800<sub>m</sub> 315°  
HdWind E.20s E.Avg E.Cru  
+5<sub>kh</sub> oo --- -3.2

VisualGlide -3  
Info on 2 lines OFF

	Dist	Dir	rEff	AltA
VALB	4.9	125°»	3.8	+1143
KONG	8.6	« 7°	6.6	+1079
SKYA	12.5	«119°	9.8	+978
ORIO	14.0	157°»	11.1	+903
BAIA	18.1	«128°	13.4	+913
CARE	25.6	«160°	18.4	+765
CARA	27.3	«154°	19.6	+722
ARZA	28.5	«142°	21.0	+666
ALZA	29.4	«33°	26.3	+384
TORL	31.4	«146°	22.2	+647
BRES	32.2	«82°	23.8	+574
LINA	35.6	«101°	25.6	+533
ROVE	37.2	«53°	29.8	+337
DOVE	37.6	«134°	26.5	+509
CARO	40.7	«62°	31.2	+312

TL.Avg GS Alt Track  
--- 1<sub>kh</sub> 1800<sub>m</sub> 315°  
HdWind E.20s E.Avg E.Cru  
+5<sub>kh</sub> oo --- -3.1

VisualGlide -3  
Info on 2 lines ON

	Dist	Dir	rEff	AltA
VALBREMBO	4.9 km			
125°»	3.8			+1144 m
KONG	8.6 km			
« 7°	6.6			+1078 m
SKYANGELS	12.5 km			
«118°	9.7			+979 m
ORIO	14.0 km			
157°»	11.1			+904 m
BAIALUPO	18.1 km			
«127°	13.4			+914 m
CAREAS	25.5 km			
«160°	18.3			+766 m

TL.Avg GS Alt Track  
--- 1<sub>kh</sub> 1800<sub>m</sub> 315°  
HdWind E.20s E.Avg E.Cru  
+5<sub>kh</sub> oo --- -3.1



## New Menus

- FLARM buttons for TRACKING option in Config 2/3 FLARM setup Stealth modes
- "Credits" (Info 2/3 > Credits)
- Radio control support driver for KRT2 (Config1/3 -> Radio)

## FAI optimizer start on leg / start on turnpoint

The FAI optimizer drawing sectors can now "on the fly" show optimization for start on either turnpoints or middle leg. It would be very confusing to see both at the same time.

Button in Display 2/3 will switch choice, and also in Analysis page.



## Glide computer

- Airspeed accuracy for Glider polar is now 0.5m/s instead of previous 1m/s
- Improved accuracy of Speed to Fly calculation

## Airspaces

- Supporting RMZ airspace zone Radio Mandatory Zone
- AG airspace token type is ignored

## New infoboxes

- Alternate1 and Alternate2 distances in nautical miles.

## Auto Zoom

In v6 the autozoom is calculated using "optimized turnpoint" (or AAT Target point) instead of center.

## Task system

- Improved FAI sectors (open second sector in 25/45% threshold transition)
- New Conical ESS turnpoint type for PG optimized task
- Best speed / climb rate for reach this turnpoint is displayed inside analysis / glide-polar screen.
- Cone slope is draw on next turnpoint "side view".
- AutoMC and Speed to fly take account of Conical ESS in Final Glide.
- Default "Base Altitude" for this turnpoint is the Altitude of turnpoint.
- Required speed for reach start on Time Gate Overlay,
- "----" is displayed when speed is to slow, "oo" when speed is too fast

## Devices

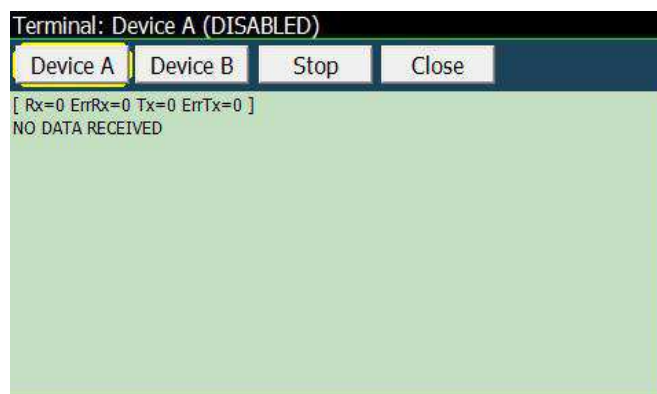
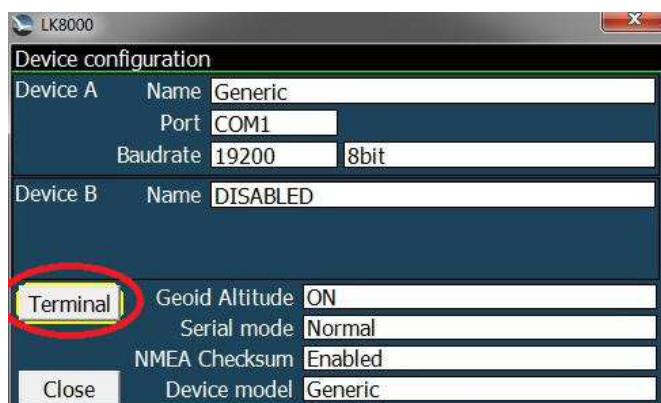
- New generic radio control driver PVCOM (NMEA splitter via Arduino in progress)
- New driver for **LXNAV Nano 3**, including task declaration
- New XCTRACER driver
- New GPSbip driver
- New Flymaster GPS driver
- NMEA checksum previously configurable in Com port setup is now part of engineering menu, and by default it is enabled. It is a very bad idea to disable NMEA checksum while using a real RS232 serial line, which is not granting data integrity during transmission.

## Simulator

New **netto vario** parameter in integrated simulator.

## Terminal Com Port monitor

In device configuration it is now possible to monitor port activity in real time.

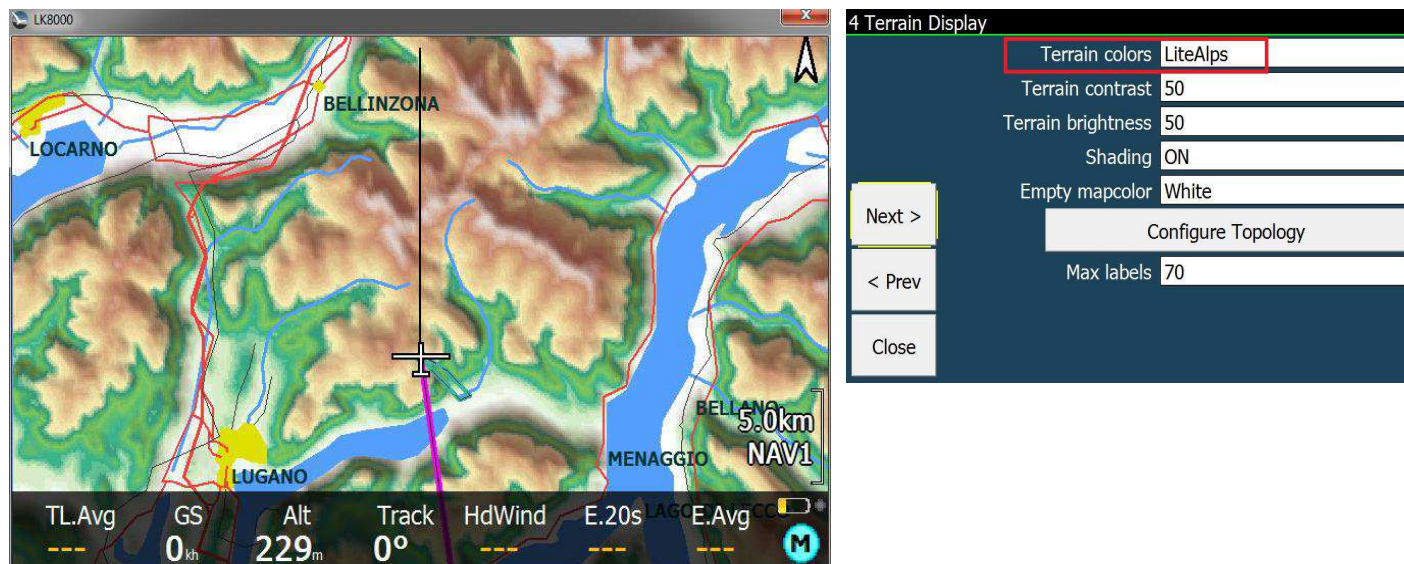


You can select anytime the desired Device A or B, and while monitoring you can suspend the data stream flow by pressing Stop. The Stop button will change to Resume. The monitor window is auto-scrolling and will report the total of received and transmitted data bytes, also accounting for errors.

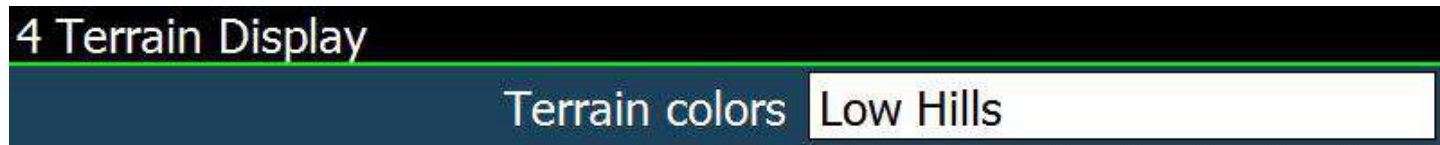
## New terrain color schemes “LiteAlps” and “Low Hills”

Two new terrain color schemes are available in system configuration page 6.

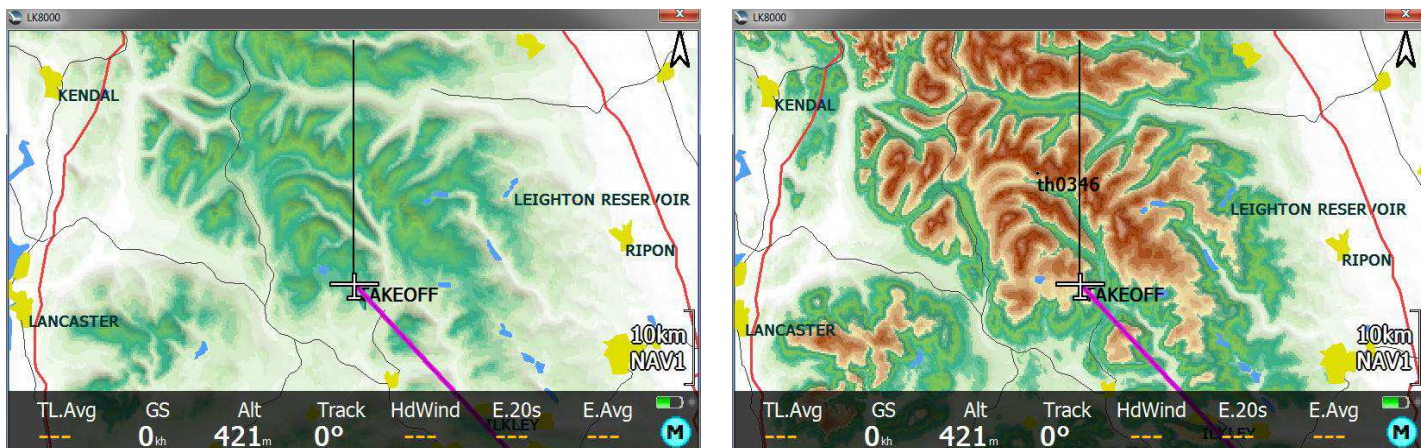
LiteAlps gives best results rendering terrain making valleys and flatlands appearing in contrast to hills and mountains around and using bright color as much as possible.



The “Low Hills” scheme is dedicated to low lands with a lot of low hills, averaging around 600-700m. This is perfect for the **UK**, but can also work beautifully in other countries.



In the two screenshots of **the same terrain**, on the left LiteAlps, on the right Low Hills.



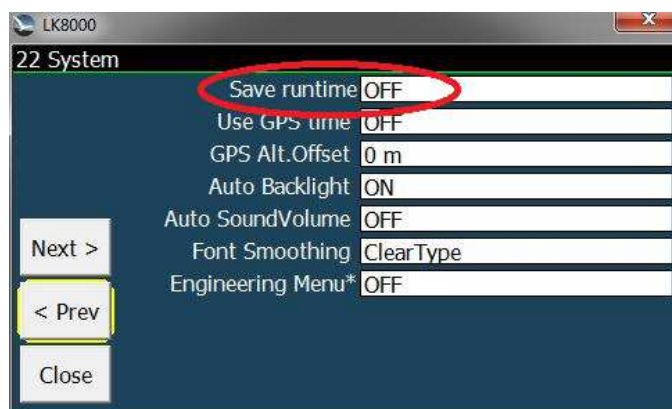


## Runtime parameters saved on exit

LK v5 was saving automatically all parameters changed in menus during runtime.

This is now optional, and by default disabled.

You can enable this option in system configuration, menu 22.



## PC version screen resolution choice

You can now choose which resolution LK should use (for example 960x572) by creating a link adding following parameters to command line:

C:\Users\yourname\Desktop\LK8000-PC.exe -x=960 -y=572

Values allowed are **240 to 4000** (pixels).

Currently squared screens (like 400x400, 600x600) are not supported by LK.

## PLUGIN FOR PARAGLIDING NO MORE NEEDED

The plugin extension for FAI-CIVL is no more needed and it is not used any more.

So there are no more plugins for LK v6.

## Other changes

- Battery information is updated every 2 seconds, no more every second, to minimize variations.
- New icon, resized for better layout on all screen resolutions
- If Team Mate is in use, then the team mate code of a waypoint will be printed aside the name while examining wp's details. This will NOT happen if the waypoint is a CUP landable (that is: the waypoint is marked as landable inside a CUP formatted file). Reason: no space for it on the screen.
- Odometer distance will not be updated while circling, unless using Car-Bike-Trekking modes.
- If not using metrics as altitude units, then use FL instead of aAlt in the bottombar.

## Fixes

- Transparency for bottom bar and airspace drawing is available on all devices
- Oracle is now much faster
- Fix 604.plr and SZD 50 polars
- \$PTAS1 NMEA sentences parsing : baro altitude can be negative on low and with high atmospheric pressure
- Since v5.0 COM port parity could not be changed by configuration, now fixed
- In Windows CE, com port could hang sometimes, now fixed.
- Various minor fixes and performance enhancements

## KOBO SUPPORT

LK works on some Kobo devices. With or without OTG kernel:

- Kobo Mini
- Kobo Glo
- Kobo GloHD
- Kobo Touch 2.0

Without OTG kernel:

- Kobo Touch ( N905B and N905C Model only )

no other models are supported.

These devices do not have a GPS inside, so you need to provide a GPS feed through either a serial port or through WiFi.

Serial ports requires internal hardware modification, or the use of a USB OTG cable and a usb to serial adapter. In this case, a special version of LK is required too, in order to provide USB OTG kernel capability.

There is no sound in Kobo.

The grey-scale e-ink display has only 16 colors, and we cannot do miracles with dithered terrain rendering. However, we have tailored all colors for dithered greyscale on Kobo at the best possible result. The Kobo version is **not** a simple greyscale version of LK8000: it is custom made concerning colors.

## Installing LK on Kobo

- Connect the Kobo to PC with a USB cable, so that it appears as a USB disk drive.
- extract the content of kobo-install.zip archive into your Kobo ( use "kobo-install-otg.zip" if you want to connect a GPS source through USB )
- Right click on file -> Extract To... -> choose "KOBOReader" USB drive
- eject and reboot the kobo
- If you have chosen to install the OTG version, then after restart on the startup screen you must see "- USB host kernel -"
- **Notice for MAC OS** users, a tip: archive contains a ".kobo" hidden folder! You may not see the **.kobo** folder because on Apple any folder beginning with a dot is considered hidden. Under MacOS it is necessary to install one among many available tools to let you visualize hidden folders.
- To exit LK and enter the Nickel environment, use the startup Kobo button on LK.  
Otherwise, after a normal exit from LK, the Kobo will go to sleep.



## Adding Maps, Airspaces, Waypoints on Kobo

- on startup screen, click on "Kobo"
- connect the kobo to your computer with usb cable
- copy Map files in "LK8000/\_Maps" folder ( get it from <http://lk8000.it/download/maps.html> )
- copy Airspace files in "LK8000/\_Airspaces" folder
- copy Waypoint files in "LK8000/\_Waypoints" folder

## Configure LK8000 software

- configure GPS source

"Menu" -> "Config" -> "Config 1/3" -> "LK8000 Setup" -> "Device Setup"

- configure Aircraft ( type polar, name, class, compID ... )

"Menu" -> "Config" -> "Config 1/3" -> "LK8000 Setup" -> "Aircraft Setup"

- change your Name ( used by IGC logger )

"Menu" -> "Config" -> "Config 1/3" -> "LK8000 Setup" -> "Pilot Setup"

- configure Map / Airspace / Waypoint

"Menu" -> "Config" -> "Config 1/3" -> "LK8000 Setup" -> "System Setup"

## Getting the track log (IGC recording of flight)

- on startup screen, click on "Kobo"
- connect the kobo to your computer with usb cable
- your track log is inside "LK8000/\_Logger" folder

## Feeding GPS signal to Kobo via WiFi on Android

- Download the app "GPS2NET" or something similar from Play Store. This application is going to use the GPS inside the smartphone to transmit a gps feed over wifi.
- From GPS2NET menu, select Settings, General, Start at boot OFF, GPS Interval 1 second.
- Check that on the main GPS2NET page there is 6000 (the later port number).
- On the smartphone enable Data Transmission, and enable Router WiFi

**Important: you must be under 3G or 2G coverage to initially do the pairing with Kobo**

- From the Kobo welcome screen, choose ***Set up over Wi-Fi***
- Search for the smartphone in the network list, and select it. If the Router Wifi on smartphone has a password you must enter it.

**The smartphone in this phase must be under 2G or 3G coverage to give Kobo an internet connection, otherwise the Kobo will disconnect immediately saying no pairing.**

- If the connection is established, in the pull down menu on the smartphone a new connected device will appear. Kobo is now connected to Android.
- On Android GPS2NET click on START. From now on, the smartphone is sending the NMEA stream of the GPS on TCP/IP, to whatever network device connecting to the smartphone on port 6000. It will say "Waiting for connection".
- Switch off the Kobo with its hardware switch. Wait until it is off and then switch it on.
- LK8000 will appear. Enter FLY mode.
- Menu, Config 2/3, LK8000 Setup, Device Setup.
- Device A: Generic
- Port: TCPClient
- IP: 192.168.43.1    Port: 6000
- Exit configuration. On the screen, GPS: No ComPort initially.

After 30-60 seconds, GPS: NO VALID FIX or even better, already a valid fix, and the clock will start running. Your Kobo has a GPS!

### **Shutdown LK8000 and Wifi on Kobo**

Terminating LK8000 with Exit will shutdown Kobo and Wifi automatically. On the smartphone no devices are connected. Enter GPS2NET and click on STOP. You can switch off Router Wifi too.

### **Normally restart LK8000 with Wifi**

Of course you don't need to do the pairing and the above procedure after the first time.

Here is what you need to do in order to restart Kobo using the old Wifi connection to android gps.

- *You don't need Data transmission enabled, and you don't need an internet connection after pairing kobo-android is done the first time*
- Enable Router Wifi
- Run GP2NET and click on START
- Switch ON the Kobo, LK8000 is starting, enter FLY mode
- Initially Kobo is not yet connected to Android. On the screen you read
- GPS: No ComPort . Wait for 30-60 seconds , and you get GPS: NO VALID FIX or a good fix with the clock running.

## **Smartphone disconnected from Kobo?**

Now that Kobo has a GPS connection to android, do the following test.

- Check LK8000, gps is running, either with NO VALID FIX or with a valid fix.
- On Android, switch off Router Wifi and/or stop GPS2NET, and/or switch off the phone.
- ON LK8000, GPS: No ComPort
- Even with no 3G or 2G connection, switch on the Router and start GPS2NET.
- After a while, LK8000 will get the GPS feed.

So in case of smartphone problems during flight, you don't have to do anything on Kobo, just fix the smartphone.

## **How to find the correct IP address of your smartphone Router Wifi**

If the connection does not work, there is a chance that the local IP address of the smartphone is not 192.168.43.1 . To find the correct address, download from Play Store an app like OS Monitor .

From OS Monitor select Connections and browse the list until you see GPS2NET.

You should see something like 192.168.1.43:6000

Search for 6000, not for other ports. The address on the left is the correct IP address to use inside LK8000. This will not change any more, since it is stable inside your Android every time you switch on Router Wifi.

## **GoFly instruments**

V4 and V5 come with LK preinstalled, and their custom piezo speaker and pressure sensor are fully supported!

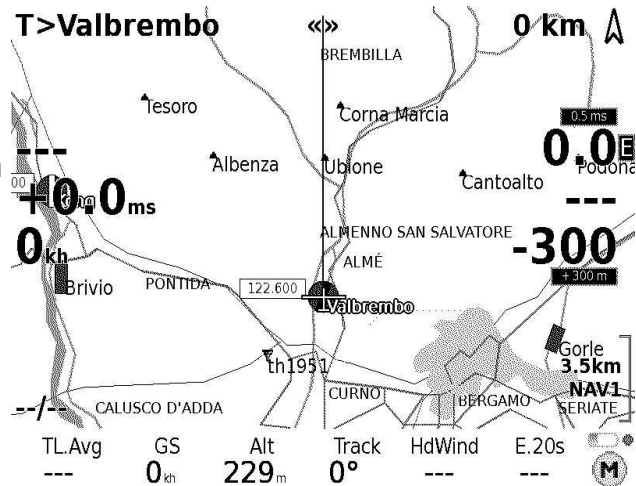


# How to configure a Kobo for best visual results

Kobo devices have an e-ink screen which features only a limited number of grey shades.

For best result, it is a good idea to use textual pages in black over white.

In the example, you can notice the bottom bar is not black but white. To achieve this look, a few easy steps in configuration are needed.



4 Terrain Display

Terrain colors	Low lands
Terrain contrast	50
Terrain brightness	50
Shading	ON
Empty mapcolor	White
Configure Topology	
Max labels	70

Next >

< Prev

Close

11 Appearance

Glider position	40 %
Landables icon	Vector
Landables style	Boxed, with unit
Landables value	ArrivalAltitude
Inverse b/w colors	ON
Waypoints Text style	Values white
Overlays color	White
Turnpoints filter	No landables
Hide units	OFF
BottomBar Opacity	100 %

Next >

< Prev

Close

Finally, since these eink screens have an higher resolution than PNAs, you may want to change the size of overlays, map items etc. to a more reasonable size.

12 Fonts

Overlay target	-1
Overlay values	-2
Map waypoints	-3
Map topology	-3
Nearest	-3
Bottom bar	-3
VisualGlide	-3
Info on 2 lines	ON

Next >

< Prev

Close

## LK8000 Radio Interface

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E.D.Klinkenberg

A modern transceiver can be externally controlled via its serial interface. This feature was originally thought to connect a second radio handling panel installed at a double seater backseat.

Now this feature is exploited by LK8000 to control the radio conveniently from within the program. It gives the possibility to change the most important radio parameters as **frequency**, **volume**, **squelch** and **dual channel watch** easily with some clicks on the touch screen.

The first LK8000 supported transceiver is the Dittel Avionics KRT2-transceiver, a wide spread device.

From a practical point of view an easily to use radio interface

- (1) reduces the workload of the pilot significantly and
- (2) promotes the willingness for radio contacts to enhance situational awareness.

To control the radio it needs a) a **physical interface** and b) a **device driver**.

Some devices (e.g. Vertica2) have a spare serial standard interface, a comfortable situation. In this case you can speak directly to the transceiver in its "own language", by a special device driver.

If you are restricted to one physical serial port (typically PNAs) all external informations (GPS, E-vario, FLARM, radio) can be handled over this one port by the help of a **special hardware multiplexer**, developed by Ullrich Heynen and provided as an open hardware project with open source controller software to be found at github.

The technical details of the hardware connection are described in a separate document.

## LK8000 configuration

### Attention!

Here is assumed that you have a working hardware link, either directly or via the multiplexer.

LK8000 supports the direct link to the KRT2 with a special KRT2-driver and the link via the multiplexer by a generic NMEA-driver named "PVCOM".

For the **direct link** go to the device configuration page:

**Menu ► Config ► Config 2/3 ► LK8000 Setup ► Device Setup**

and choose Dittel KRT2 as device B at the appropriate com-port and baud rate (9600), see fig. 1.

**Fig. 1:** LK8000 device configuration page, device B configured to the native Dittel KRT2 driver bounded to com-port COM2 at 9600 baud, 8N1

Device configuration			
Device A	Name	Generic	
	Port	COM1	
	Baudrate	57600	8bit
Device B	Name	Dittel KRT2	
	Port	COM2	
	Baudrate	9600	8bit
Terminal	Geoid Altitude	ON	
	Serial mode	Normal	
	NMEA Checksum	Enabled	
	Device model	Generic	
Close			

In the case of the **multiplexer link** at the same configuration page

**Menu** ► **Config** ► **Config 2/3** ► **LK8000 Setup** ► **Device Setup**

choose the PVCOM-driver as the device B, see fig. 2

**Fig. 2:** Configuration of device B configuration as radio with the radio-NMEA-PVCOM driver using the same com-port COM1 as Device A, the most reliable GPS-source (and other NMEA devices)

Device configuration			
Device A	Name	Generic	
	Port	COM1	
	Baudrate	38400	8bit
Device B	Name	PVCOM	
	Port	COM1	
	Baudrate	38400	8bit
Terminal	Geoid Altitude	ON	
	Serial mode	Normal	
	NMEA Checksum	Enabled	
	Device model	Generic	
Close			

With the help of the terminal you can check the traffic on both ports.

## Controlling the radio from within LK8000

There are several possibilities to control your radio from within LK8000.

- (1) Access by the menu
- (2) Access by the waypoints chooser
- (3) Access by the surroundings page

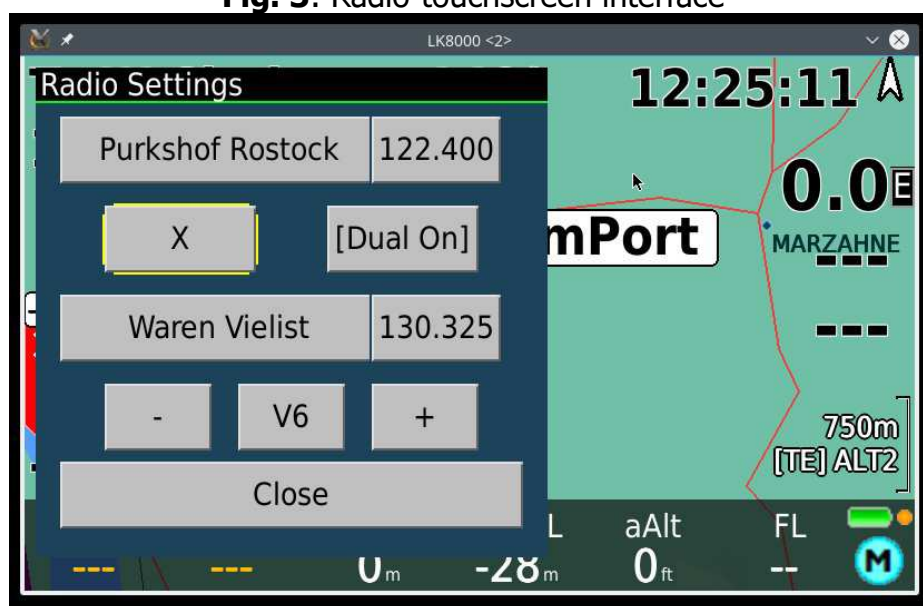
### Access by the menu:

With

**Menu ► Config ► Setup Radio**

you reach the radio config box, fig. 3:

**Fig. 3:** Radio-touchscreen interface



The interface is widely self-explanatory:

- The two current radio-channels with names and frequencies are shown with the active one on top.
- The [X]-button exchanges the two channels.
- The [Dual-On/Off]-button activates/deactivates the dual channel watch.
- Volume or squelch changes are chosen by the [V/S]-button, the value itself can be changed by the [+] - or [-]-button and is indicated by the appended number to the [V/S]-button.

A channel of the two can be changed individually by either click on the name field or the frequency field.

By clicking the name field you choose the name of the channel from the waypoint chooser, see fig. 4.



**Fig. 4:** Waypoint chooser



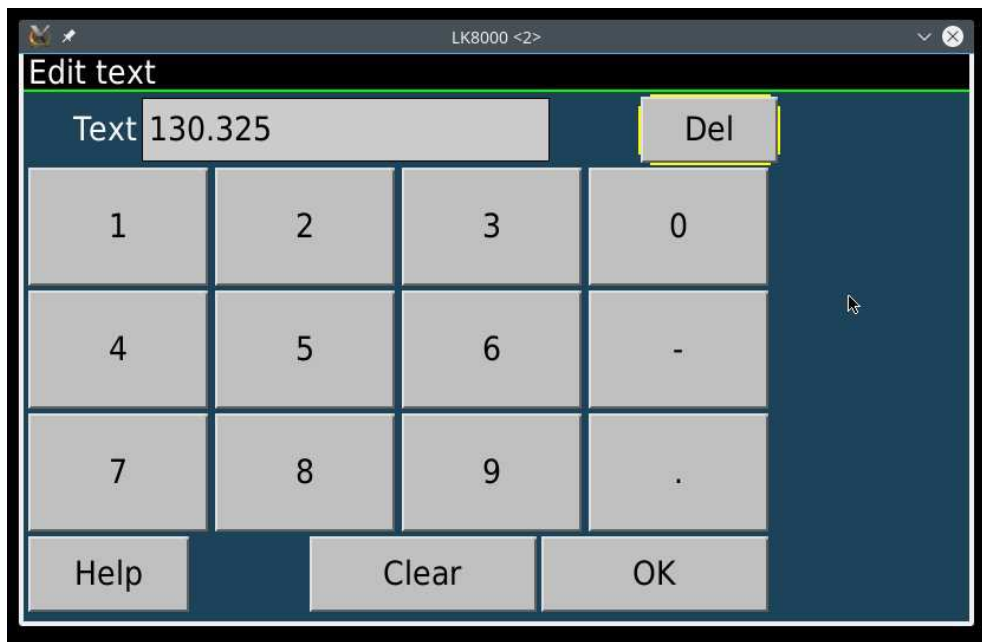
Choosing a waypoint, you can set the frequency by the [Output Frequency]-button, fig. 5.

**Fig. 5:** Frequency setting button



There is also the possibility to set the frequency within the radio interface by hand. It can be done by clicking on a frequency field and then you get a numerical input pad, see fig. 6.

**Fig. 6:** Numerical frequency input



Here you choose the wanted frequency and if it is known from within your waypoint file, the name will be resolved and shown after clicking [OK].

The input mode of the numerical pad is somewhat smart and resolves also e.g.:

121.5	=>	121.500MHz
129	=>	129.000MHz
1225	=>	122.500MHz
13115	=>	131.150MHz

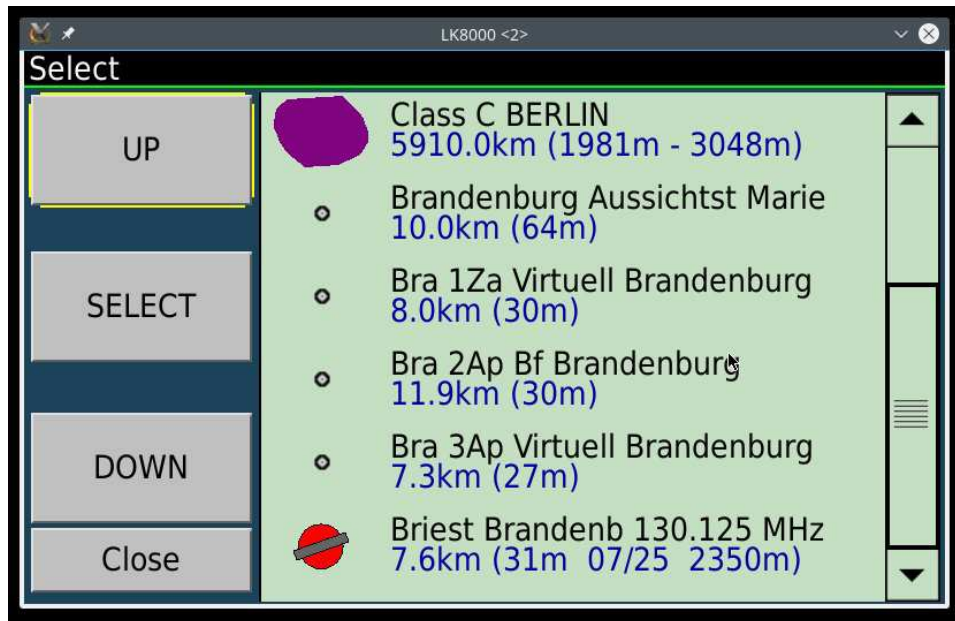
#### **Access by the waypoints chooser:**

Choose a waypoint as for navigational purposes and set the linked frequency, see fig. 5.

#### **Access by the surroundings page:**

After a long click on an interesting part of the map you get a list with all interesting things in your surrounding, fig. 7.

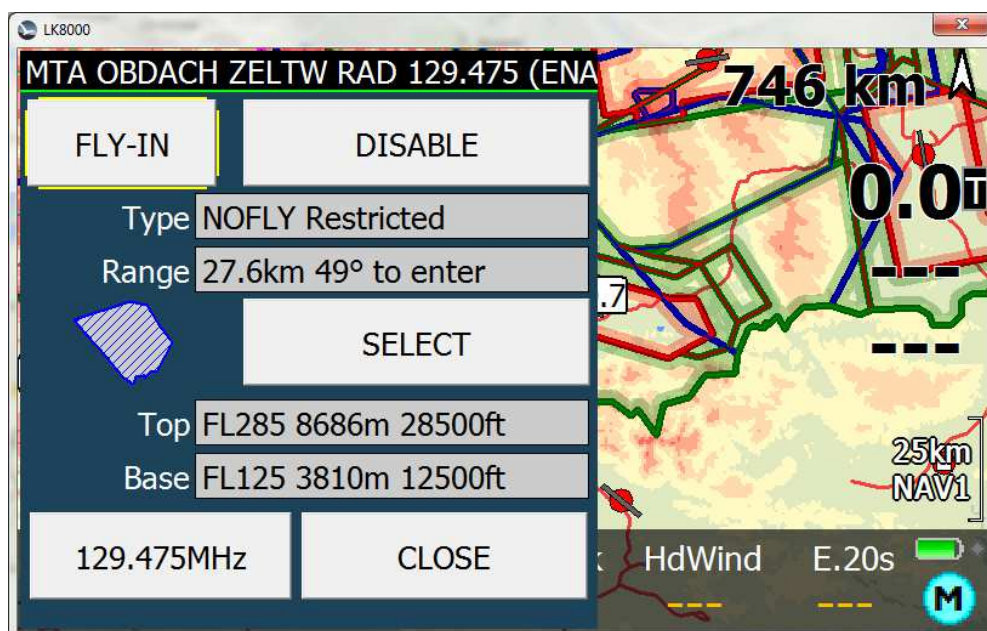
**Fig. 7:** Surroundings list



Choose an item with a frequency and select it. From the waypoint dialog you can set the frequency as described, see fig.5.

**Note**, if an airspace name here includes a valid frequency there will also be a radio frequency setting button in the airspace detail dialog!

**Fig. 8:** Airspace details with frequency button



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